# A range test method for an inverse source problem

### Rainer Kress University of Göttingen

Joint work with:

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**Incident Wave:** 

$$u^{i}(x) = \sum_{j=1}^{n} c_{j} \Phi(x, s_{j})$$

## Outline

- The inverse problem
- Iterative solution
- Range test method
- Tikhonov regularization
- Examples

Idea: For nonlinear inverse scattering problem, design an ill-posed linear integral equation of the form

$$A\varphi = f_z$$
 or  $A_{\Gamma}\varphi = f$ 

with a right hand side f depending on a point z or an operator A depending on a closed curve  $\Gamma$ .

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$$A\varphi = f_z$$
 or  $A_{\Gamma}\varphi = f$ 

with a right hand side f depending on a point z or an operator A depending on a closed curve  $\Gamma$ . Via solvability of this equation decide on whether

- the point z belongs to the unknown scatterer or not
- or the scatterer lies in the interior of the curve Γ or not.

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• *D* bounded smooth domain in  $\mathbb{R}^2$ 

• 
$$u^s \in C(\mathbb{R}^2 \setminus D) \cap C^2(\mathbb{R}^2 \setminus \overline{D})$$

Incident Wave:  $u^{i}(x) = \sum_{j=1}^{n} c_{j} \Phi(x, s_{j})$ 

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Incident Wave:  $u^{i}(x) = \sum_{j=1}^{n} c_{j} \Phi(x, s_{j})$  *D* bounded smooth domain in ℝ<sup>2</sup> *u<sup>s</sup>* ∈ *C*(ℝ<sup>2</sup>\*D*) ∩ *C*<sup>2</sup>(ℝ<sup>2</sup>\*D*)

Helmholtz equation:

$$\Delta u^s + k^2 u^s = 0$$
 in  $\mathbb{R}^2 \setminus \overline{D}$ 



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Sommerfeld radiation condition:

$$\frac{\partial u^{s}}{\partial r} - iku^{s} = o\left(\frac{1}{\sqrt{r}}\right), \ r = |x| \to \infty$$

## **Fundamental solution**

$$\Phi(x,y) = \frac{i}{4}H_0^{(1)}(k|x-y|), \quad x \neq y$$

$$-\Delta\Phi(.,y)-k^{2}\Phi(.,y)=\delta_{y}$$

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Helmholtz equation ( $u := u^i + u^s$ ):

$$-\Delta u - k^2 u = \sum_{j=1}^n c_j \delta_{s_j}$$
 in  $\mathbb{R}^2 ackslash \overline{D}$ 

Boundary condition:

$$u = 0$$
 on  $\partial D$ 

Incident Wave:  $u^{i}(x) = \sum_{j=1}^{n} c_{j} \Phi(x, s_{j})$  Sommerfeld radiation condition:

$$\frac{\partial u}{\partial r} - iku = o\left(\frac{1}{\sqrt{r}}\right), \ r = |x| \to \infty$$

### The inverse problem

$$\begin{cases} -\Delta u - k^2 u = \sum_{j=1}^n c_j \delta_{s_j} & \text{in } \mathbb{R}^2 \setminus \overline{D} \\ u = 0 \text{ on } \partial D \\ \frac{\partial u}{\partial r} - iku = o\left(\frac{1}{\sqrt{r}}\right), \quad r = |x| \to \infty \end{cases}$$

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### The inverse problem

$$\begin{cases} -\Delta u - k^2 u = \sum_{j=1}^n c_j \delta_{s_j} & \text{in } \mathbb{R}^2 \setminus \overline{D} \\ u = 0 \text{ on } \partial D \\ \frac{\partial u}{\partial r} - iku = o\left(\frac{1}{\sqrt{r}}\right), \quad r = |x| \to \infty \end{cases}$$

### Inverse source problem

Given:

the domain D

• the normal derivative 
$$\frac{\partial u}{\partial v} = g$$
 on  $\partial D$ 

Find:

positions s<sub>i</sub> and intensities c<sub>i</sub> of the sources

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Ben Abda, Ben Hassen, Leblond, and Majoub 2008

El Badia and Ha-Duong 2000

Leblond, Paduret, Rigat, and Zghal 2008

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### Identifiability

The positions  $s_j$  and intensities  $c_j$  of the sources are uniquely determined by the normal derivative  $\frac{\partial u}{\partial \nu} = g$  on  $\partial D$ . (Follows from Holmgren's theorem.)

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### Non-linearity

The inverse problem is non-linear with respect to the positions  $s_i$  of the sources.

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### Non-linearity

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### III-posedness

The solution of the inverse problem does not depend continuously on the data.

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### Total field:

$$\begin{cases} -\Delta u - k^2 u = \sum_{j=1}^n c_j \delta_{s_j} & \text{in } \mathbb{R}^2 \setminus \overline{D} \\ u = 0, \quad \frac{\partial u}{\partial \nu} = g & \text{on } \partial D \\ \frac{\partial u}{\partial r} - iku = o\left(\frac{1}{\sqrt{r}}\right), \quad r = |x| \to \infty \end{cases}$$

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### Green's theorem:

For any solution *v* of the Helmholtz equation in  $\mathbb{R}^2 \setminus \overline{D}$  satisfying the radiation condition we have

$$\sum_{j=1}^n c_j v(s_j) = \int_{\partial D} vg \, ds$$

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### **Reciprocity relation**

For any radiating solution v to the Helmholtz equation in  $\mathbb{R}^2 \setminus \overline{D}$  we have

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Choose test functions  $v_1, \ldots v_m$  with  $m \ge 3n$  to obtain overdetermined system of equations

$$\sum_{j=1}^{n} c_{j} v_{\ell}(s_{j}) = \int_{\partial D} v_{\ell} g \, ds, \quad \ell = 1, \dots, m.$$

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Solve iteratively via linearization, i.e., by Newton iterations. Questions:

- How to choose the test functions  $v_{\ell}$ ?
- How to obtain an initial guess?

Denote by *N* the Neumann-to-Dirichlet operator for the exterior domain  $\mathbb{R}^2 \setminus \overline{D}$ , that is,

$$\boldsymbol{N}: \left. \frac{\partial \boldsymbol{v}}{\partial \boldsymbol{\nu}} \right|_{\partial \boldsymbol{D}} \mapsto \left. \boldsymbol{v} \right|_{\partial \boldsymbol{D}},$$

for solutions v to Helmholtz equation in  $\mathbb{R}^2 \setminus \overline{D}$  satysfying the radiation condition.

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Denote by  $u_0$  be the solution to the exterior Neumann problem with boundary condition

$$\frac{\partial u_0}{\partial \nu} = g \quad \text{on } \partial D,$$

that is,  $Ng = u_0|_{\partial D}$ .

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We can represent as a single-layer potential

$$u(x)-u_0(x)=\int_{\partial D}\Phi(x,y)\psi(y)ds(y)+\int_{\Gamma}\Phi(x,y)\varphi(y)ds(y),\quad x\in G,$$

if and only if  $s_j \notin G$  for  $j = 1, 2, \ldots, n$ .



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if and only if  $s_j \notin G$  for  $j = 1, 2, \ldots, n$ .

Use boundary conditions  $u - u_0 = -Ng$  and  $\partial_{\nu}u - \partial_{\nu}u_0 = 0$  on  $\partial D$  to derive integral equation of the first kind for  $\varphi$ .

Define compact operators  $V, W, A : L^2(\Gamma) \to L^2(\partial D)$  by

$$(V\varphi)(x) := \int_{\Gamma} \Phi(x,y)\varphi(y) \, ds(y), \quad x \in \partial D,$$

and

$$(W\varphi)(x) := \int_{\Gamma} \frac{\partial \Phi(x, y)}{\partial \nu(x)} \varphi(y) \, ds(y), \quad x \in \partial D.$$

and A := -V + NW.

### Theorem

Assume that  $k^2$  is not a Dirichlet eigenvalue of the negative Laplacian neither for *G* nor for *D*. Then the ill-posed linear operator equation

$$A\varphi = Ng$$

is solvable for  $\varphi$  if and only if  $s_j \notin G$  for j = 1, 2, ..., n.

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### Question: How to check solvability numerically?

Approximate the ill-posed equation

 $A\varphi = f$ 

by the well-posed equation

$$\alpha\varphi_{\alpha} + \mathbf{A}^*\mathbf{A}\varphi_{\alpha} = \mathbf{A}^*f$$

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Assume that A and A\* are injective. Then the limit

 $\lim_{\alpha\to 0}\varphi_{\alpha}$ 

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Assume that A and A\* are injective. Then the limit

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exists if and only if the ill-posed equation is solvable. Check solvability:

- Perform Tikhonov regularization for a couple of small regularization parameters.
- If the solution φ<sub>α</sub> changes only slightly, then the equation is considered solvable.
- Otherwise, the equation is considered unsolvable.

### Theorem

## The operator A = -V + NW is injective provided $k^2$ is not a Dirichlet eigenvalue of the negative Laplacian for $D \cup G$ .

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The operator A = -V + NW is injective provided  $k^2$  is not a Dirichlet eigenvalue of the negative Laplacian for  $D \cup G$ .

#### Theorem

The operator A := -V + NW has dense range provided  $k^2$  is not a Dirichlet eigenvalue of the negative Laplacian for D.

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$$\begin{aligned} \mathbf{A}\varphi &= \mathbf{N}\mathbf{g}\\ \alpha\varphi_{\alpha} &+ \mathbf{A}^{*}\mathbf{A}\varphi_{\alpha} &= \mathbf{A}^{*}\mathbf{N}\mathbf{g} \end{aligned}$$

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- Start with a circle  $\Gamma$  close to  $\partial D$ .
- Enlarge the circle while the equation is solvable.



$$\begin{aligned} \mathbf{A} \varphi &= \mathbf{N} \mathbf{g} \\ \alpha \varphi_{\alpha} + \mathbf{A}^* \mathbf{A} \varphi_{\alpha} &= \mathbf{A}^* \mathbf{N} \mathbf{g} \end{aligned}$$

- Start with a circle  $\Gamma$  close to  $\partial D$ .
- Enlarge the circle while the equation is solvable.
- When it becomes unsolvable, use a circle with a bump for Γ and rotate it while testing solvability.























$$\varphi(x) + \int_0^1 K(x, y) \varphi(y) \, dy = f(x), \quad 0 \le x \le 1$$

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$$\varphi(x) + \int_0^1 K(x, y) \varphi(y) \, dy = f(x), \quad 0 \le x \le 1$$

Approximate solution via trapezoidal rule:

$$\varphi_{\ell} + h \sum_{j=0}^{n} K(\ell h, jh) \varphi_j = f(\ell h), \quad \ell = 0, 1, \dots, n$$

Linear system for approximations  $\varphi_{\ell} \approx \varphi(\ell h)$ .

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$$\varphi(x) - \frac{1}{2} \int_0^1 (x+1)e^{-xy}\varphi(y)dy = e^{-x} - \frac{1}{2} + \frac{1}{2}e^{-(x+1)}$$

has solution  $\varphi(x) = e^{-x}$ 



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has solution  $\varphi(x) = e^{-x}$ 

### Trapezoidal rule

n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
4	-0.007146	-0.010816	-0.015479
8	-0.001788	-0.002711	-0.003882
16	-0.000447	-0.000678	-0.000971
32	-0.000112	-0.000170	-0.000243

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has solution  $\varphi(x) = e^{-x}$ 

### Simpson rule

п	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
4	-0.00006652	-0.00010905	-0.00021416
8	-0.00000422	-0.00000692	-0.00001366
16	-0.00000026	-0.00000043	-0.0000086
32	-0.00000002	-0.0000003	-0.00000005

$$\int_0^1 K(x,y)\varphi(y)\,dy=f(x),\quad 0\leq x\leq 1$$

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$$\int_0^1 \mathcal{K}(x,y)\varphi(y)\,dy=f(x),\quad 0\leq x\leq 1$$

Approximate solution via trapezoidal rule:

$$h\sum_{j=0}^{n} K(\ell h, jh)\varphi_j = f(\ell h), \quad \ell = 0, 1, \dots, n$$

Linear system for approximations  $\varphi_{\ell} \approx \varphi(\ell h)$ .

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$$\int_0^1 (x+1) e^{-xy} \varphi(y) dy = 1 - e^{-(x+1)}$$

has solution  $\varphi(x) = e^{-x}$ 



$$\int_0^1 (x+1) e^{-xy} \varphi(y) dy = 1 - e^{-(x+1)}$$

has solution  $\varphi(x) = e^{-x}$ 

Trapezoidal rule

n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
4	0.4057	0.3705	0.1704
8	-4.5989	14.6094	-4.4770
16	-8.5957	2.2626	-153.4805
32	3.8965	-32.2907	22.5570
64	-88.6474	-6.4484	-182.6745

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$$\int_0^1 (x+1) e^{-xy} \varphi(y) dy = 1 - e^{-(x+1)}$$

has solution  $\varphi(x) = e^{-x}$ 

### Simpson rule

n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
4	0.0997	0.2176	0.0566
8	-0.5463	6.0868	-1.7274
16	-15.4796	50.5015	-53.8837
32	24.5929	-24.1767	67.9655
64	23.7868	-17.5992	419.4284

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$$\int_0^1 (x+1)e^{-xy}\varphi(y)dy = 1 - e^{-(x+1)} \text{ has solution } \varphi(x) = e^{-x}$$

$\alpha = 10^{-8}$	n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
	16	-0.000359	-0.000002	0.000209
	32	-0.000193	-0.000014	0.000149
	64	-0.000183	0.000015	0.000145
	128	-0.000182	-0.000015	0.000145

$\alpha = 10^{-10}$	n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
	16	-0.000455	-0.000022	0.000277
	32	-0.000042	-0.000001	0.000017
	64	-0.000011	-0.000000	-0.000001
	128	-0.000008	-0.000002	0.000002

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$$\int_0^1 (x+1)e^{-xy}\varphi(y)dy = 1 - e^{-(x+1)}$$
 has solution  $\varphi(x) = e^{-x}$ 

$\alpha = 10^{-8}$	n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
	32	0.999806	0.606516	0.368028
	64	0.999816	0.606515	0.368024
	128	0.999817	0.606515	0.368024

$\alpha = 10^{-10}$	n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
	32	0.999957	0.606528	0.367896
	64	0.999988	0.606529	0.367878
	128	0.999991	0.606527	0.367881

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$$\int_0^1 (x+1)e^{-xy}\varphi(y)dy = \frac{1}{2} - \left|\frac{1}{2} - x\right|$$
 has no solution

$\alpha = 10^{-8}$	n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
	32	12.3108	61.1597	-178.454
	64	12.2942	61.1537	-178.438
	128	12.2931	61.1533	-178.437

$\alpha = 10^{-10}$	n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
	32	1180.66	419.818	514.502
	64	1181.06	419.593	513.926
	128	1181.09	419.579	513.891

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$$\int_0^1 (x+1)e^{-xy}\varphi(y)dy = 1 \quad ???$$

$\alpha = 10^{-8}$	n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
	32	-24.1059	-8.0327	45.9362
	64	-24.1052	-8.0314	45.9311
	128	-24.1052	-8.0314	45.9308

$\alpha = 10^{-10}$	n	<i>x</i> = 0	<i>x</i> = 0.5	<i>x</i> = 1
	32	-84.0948	-10.3093	131.5763
	64	-84.1591	-10.3218	131.5725
	128	-84.1632	-10.3226	131.5722

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### Example for inverse source problem



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### Example for inverse source problem



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### Example for inverse source problem





Alves, C., Kress, R. and Serranho, P. Iterative and range test method for an inverse source problem for acoustic waves. Inverse Problems **25**, 055055 (2009)