

Uniqueness of Shalika Models

Chufeng Nien*

Abstract

Let \mathbb{F}_q be a finite field of q elements, \mathcal{F} a p -adic field and D is a quaternion division algebra over \mathcal{F} . This paper proves uniqueness of Shalika models for $\mathrm{GL}_{2n}(\mathbb{F}_q)$ and $\mathrm{GL}_{2n}(D)$, and re-obtain uniqueness of Shalika models for $\mathrm{GL}_{2n}(\mathcal{F})$,¹ for any $n \in \mathbb{N}$.

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1 Introduction

Let \mathbb{F}_q denote a finite field of q elements, and \mathcal{F} denote a p -adic field. Let F be one of the above fields, and $D = D_{\mathcal{F}}$ a quaternion division algebra over

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¹Uniqueness of Shalika models for GL_{2n} over p -adic fields was first proved in ‘Uniqueness of linear periods’, by H. Jacquet and S. Rallis via the verification of multiplicity freeness of linear models and the fact: existence of Shalika models of GL_{2n} implying existence of linear models .

\mathcal{F} . Denote by Mat_n be the space of n-by-n matrices over F . Through out, ψ_0 denotes a nontrivial, complex, additive character of F .

Given D a quaternion division algebra over \mathcal{F} , then there exists a basis $\{1, i, j, k\}$ for D and the multiplication table is given by

	1	i	j	k
1	1	i	j	k
i	i	α	k	αj
j	j	$-k$	β	$-\beta i$
k	k	$-\alpha j$	βi	$-\alpha \beta$

for some suitable $\alpha, \beta \in \mathcal{F}^*$.

For $z = a + bi + cj + dk \in D$ with $a, b, c, d \in \mathcal{F}$, define the **conjugation** of z by $\bar{z} = a - bi - cj - dk$. Note that $\overline{z_1 \cdot z_2} = \bar{z}_2 \cdot \bar{z}_1$, i.e. it is an anti-involution on D (viewed as a multiplicative group). (An **anti-involution** τ of a group G is an operator on G so that $(gh)^\tau = h^\tau g^\tau, g, h \in G$ and $\tau^2 = id$.) Also we define two maps: **reduced norm** N and **reduced trace** Tr on D by $Nz = z\bar{z}$, $Trz = z + \bar{z}$. There is an **embedding** $\iota : D \hookrightarrow \text{GL}(2, K)$ defined by

$$\begin{aligned} z &= a + bi + cj + dk = (a + bi) + (c + di)j \\ &= z_1 + z_2 j \mapsto \begin{pmatrix} z_1 & z_2 \beta \\ \bar{z}_2 & \bar{z}_1 \end{pmatrix}, \end{aligned}$$

where $K = \mathcal{F}(\sqrt{\alpha})$. Then $Trz = tr(\iota z), z \in D$, where “ tr ” is the trace map on matrices. Under this embedding, D is a closed subgroup of $\text{GL}(2, K)$. This embedding can be naturally extended to

$$\iota : \text{GL}(n, D) \hookrightarrow \text{GL}(2n, K).$$

Let A be either the field F (one of the $\mathbb{F}_q, \mathcal{F}$) or the quaternion division algebra D . In $\text{GL}_{2n}(A)$, denote

$$d(g) = \begin{pmatrix} g & 0 \\ 0 & g \end{pmatrix}, g \in \text{GL}_n \text{ and } u(X) = \begin{pmatrix} I_n & X \\ & I_n \end{pmatrix}, X \in \text{Mat}_n.$$

Let $M_n = \{d(g) | g \in \text{GL}_n\}, U_n = \{u(X) | X \in \text{Mat}_n\}$; and $S_n = M_n U_n$. A **Shalika character** on S_n is given by

$$\psi_n(d(g)u(X)) = \begin{cases} \psi_0(trX), & \text{for } s \in S_n(F) \\ \psi_0(tr(\iota X)), & \text{for } s \in S_n(D) \end{cases}.$$

By abusing notation, we abbreviate $\psi_0(\text{tr}(\iota X))$ by $\psi_0(\text{tr} X)$ for $X \in \text{Mat}_n(D)$ since no confusion should occur. Moreover, we will always refer to smooth representations when we talk about representations of groups other than finite groups.

Let ρ be an irreducible representation of $\text{GL}_{2n}(A)$.

Definition 1.1. A linear functional $\Lambda_\rho : V_\rho \mapsto \mathbb{C}$ is called a **Shalika functional** of V_ρ if it satisfies

$$\Lambda_\rho(\rho(s)v) = \psi_n(s)\Lambda_\rho(v) \text{ for all } s \in \text{S}_n \text{ and } v \in V_\rho.$$

We say that V_ρ has a **Shalika model** if there exists a nontrivial Shalika functional Λ_ρ satisfying the above equation. This definition is equivalent to

$$\dim \text{Hom}_{\text{GL}_{2n}}(\rho, \text{Ind}_{\text{S}_n}^{\text{GL}_{2n}} \psi_n) \geq 1,$$

since $\text{Hom}_{\text{GL}_{2n}}(\rho, \text{Ind}_{\text{S}_n}^{\text{GL}_{2n}} \psi_n) \cong \text{Hom}_{\text{S}_n}(\rho|_{\text{S}_n}, \psi_n)$ by reciprocity.

Definition 1.2. Given a representation π of a group G , we say that π is **multiplicity free** or possesses the **uniqueness property** if $\dim \text{Hom}_G(\rho, \pi) \leq 1$, for any irreducible representation ρ of G .

Definition 1.3. Let $\pi = \text{Ind}_L^{\text{GL}_{2n}} 1$, where $L = \left\{ \begin{pmatrix} g_1 & \\ & g_2 \end{pmatrix}, g_i \in \text{GL}_n \right\}$, and 1 denotes the trivial representation of $\text{GL}_n \times \text{GL}_n$. We say that V_ρ has a **linear model** if there exists a nontrivial intertwining operator from V_ρ to π .

For general linear groups over non-archimedean local field, uniqueness of Shalika models is proved in [JR] via the verification of the multiplicity freeness of linear models. Classification of Shalika models is not yet completely established. In [Sa], Y. Sakellaridis showed necessary and sufficient conditions for an irreducible unramified principal series admitting Shalika models. In [JiS2], D. Jiang and D. Soudry showed a certain group of representations possessing Shalika models. In [JiQ], D. Jiang and Y. J. Qin defined a generalized Shalika model for $\text{SO}(4n)$ and found the relationship between this model and Shalika model of $\text{GL}(2n)$. The study of Shalika models interacts intensively with other related subjects. Let π be an irreducible cuspidal automorphic representation of $\text{GL}_{2n}(\mathbb{A})$, where \mathbb{A} is the Adele ring of a number field F . Then the following statements are equivalent:

1. π is the image of Langlands functorial lifting from SO_{2n+1} .

2. π has a nonzero Shalika period.
3. The exterior square L -function $L(s, \pi, \wedge^2)$ has a simple pole at $s = 1$.

The theory has been established over years through the work of many authors in [JaS]; [CKPSS]; [GRS]; [Ki], [JiS1] and [Ji1].

Generalizations to the case of (quaternion) division algebras have been studied by various Mathematicians. In ‘Kirillov theory of $\mathrm{GL}_2(D)$, where D is a division algebra over a non-Archimedean local field’, D. Prasad and A. Raghuram have showed the uniqueness of Shalika model and established the self-duality of irreducible representations admitting Shalika models on $\mathrm{GL}_2(D)$. Moreover, some extensions of the above theory (regarding to the poles of the exterior square L -function and non-vanishing of Shalika periods) in the case of $\mathrm{GL}_2(D)$ is given by H. Jacquet and K. Martin in [JM]. Moreover, they stated a conjecture (Jacquet-Martin conjecture) relating the existences of Shalika models for representations of $\mathrm{GL}_{2n}(D)$ and $\mathrm{GL}_{4n}(\mathcal{F})$, which is now a theorem of [GT] by W. T. Gan and S. Takeda in the case of $\mathrm{GL}_2(D)$ and $\mathrm{GL}_4(\mathcal{F})$. In this paper we will show uniqueness of Shalika models for GL_{2n} , $n \in \mathbb{N}$ in the setting of p -adic fields, finite fields and p -adic quaternion division algebras. We expect that the uniqueness of Shalika models for $\mathrm{GL}_{2n}(D)$ (or even $\mathrm{GL}_{2n}(\mathbb{F}_q)$) could be proved useful in the near future. Here we present the main theorems.

Theorem 3.2 For any $n \in \mathbb{N}$, let $G = \mathrm{GL}_{2n}(\mathbb{F}_q)$, where \mathbb{F}_q is a finite field. Then

$$\dim \mathrm{Hom}_G(\rho, \mathrm{Ind}_{\mathbb{S}_n}^G \psi_n) \leq 1,$$

for any irreducible representation of G .

Theorem 3.4 Let $G = \mathrm{GL}_{2n}$ over either a p -adic field \mathcal{F} or a quaternion division algebra D over \mathcal{F} . Then

$$\dim \mathrm{Hom}_G(\rho, \mathrm{Ind}_{\mathbb{S}_n(A)}^G \psi_n) \leq 1,$$

for any irreducible representation of G .

2 Common Strategy

Given a finite group G , it is known that a representation V_π of G is multiplicity free if and only if the endomorphism algebra $\mathrm{Hom}_G(V_\pi, V_\pi)$ is abelian.

Moreover, when $V_\pi = \text{Ind}_H^G \rho$ is an induced representation, $\text{Hom}_G(V_\pi, V_\pi)$ is explicitly characterized by Mackey Theorem.

Theorem 2.1. (*Mackey's Theorem*) *Let G be a finite group. As a vector space, $\text{Hom}_G(\text{Ind}_{H_1}^G \pi_1, \text{Ind}_{H_2}^G \pi_2)$ is isomorphic to the space of functions*

$$\Delta : G \mapsto \text{Hom}_{\mathbb{C}}(\pi_1, \pi_2) \text{ satisfying}$$

$$\Delta(h_2 g h_1) = \pi_2(h_2) \circ \Delta(g) \circ \pi_1(h_1), \text{ for } h_1 \in H_1, h_2 \in H_2.$$

Given such a function Δ , the corresponding intertwining operator

$$L \in \text{Hom}_G(\text{Ind}_{H_1}^G \pi_1, \text{Ind}_{H_2}^G \pi_2) \text{ is given by } L(f_1) = \Delta * f_1 \text{ for } f_1 \in \text{Ind}_{H_1}^G \pi_1,$$

where the convolution

$$\Delta * f_1(x) = \frac{1}{|G|} \sum_{g \in G} \Delta(xg^{-1}) f_1(g).$$

*Epecially, when $H_1 = H_2, \pi_1 = \pi_2$, the $\text{Aut}_G(\text{Ind}_{H_1}^G \pi_1)$ is isomorphic to $(\mathfrak{S}, *)$ as an algebra, where the multiplication is the convolution given by*

$$\Delta_1 * \Delta_2(g) = \sum_{x \in G} \Delta_1(gx^{-1}) \Delta_2(x), \Delta_i \in \mathfrak{S}.$$

In order to show that the endomorphism algebra is abelian, identifying an anti-involution to interchange the order of factors is a common strategy.

The analogue of this method in p -adic case is ‘Gelfand-Kazhdan criterion’, which is first investigated in [GK] and further investigated by [BZ1] and [Gr1].

Let $C_c^\infty(X)$ denote the space of smooth, compactly supported functions on a l -adic space X (in the sense of [BZ1]). Let $\mathfrak{D}(X)$ denote the space of linear functionals on $C_c^\infty(X)$. Given a p -adic group G , define actions L_g and R_g on $G; C_c^\infty(G)$ and $\mathfrak{D}(G)$ as the following:

$$L_g \cdot x = gx; \quad R_g \cdot x = xg^{-1};$$

$$(L_g \cdot f)(x) = f(g^{-1}x); \quad (R_g \cdot f)(x) = f(xg);$$

$$(L_g \cdot T)(f) = T(L_{g^{-1}} \cdot f); \quad (R_g \cdot T)(f) = T(R_{g^{-1}} \cdot f),$$

where $g, x \in G; f \in C_c^\infty(G)$ and $T \in \mathfrak{D}(G)$.

Theorem 2.2. (*[Ga], Gelfand-Kazhdan Criterion*) Let ψ and ψ^τ be characters of a closed unimodular subgroup H of G . Suppose that there is an anti-involution τ of G so that τ stabilizes H , $\psi(h^\tau) = \psi^\tau(h)$, and τ acts trivially on all distributions T so that

$$T(L_h\eta) = \psi(h) \cdot T(\eta); \quad T(R_h\eta) = \psi^\tau(h)^{-1} \cdot T(\eta) \text{ for } \eta \in C_c^\infty(G).$$

Then

$$\dim \text{Hom}_G(\pi; \text{Ind}_H^G \psi) \cdot \dim \text{Hom}_H(\text{Res}_H^G \tilde{\pi}; \psi^\tau) \leq 1,$$

where π is any irreducible representation of G and $\tilde{\pi}$ its contragredient.

3 Main Theorems

Define anti-involutions on $\text{GL}_n(\mathbb{F})$ and $\text{GL}_n(D)$ respectively by

$$\tau_n : \text{GL}_{2n}(\mathbb{F}) \mapsto \text{GL}_{2n}(\mathbb{F}), g \mapsto w_{2n} g^t w_{2n}^{-1},$$

$$\tau_n : \text{GL}_{2n}(D) \mapsto \text{GL}_{2n}(D), g \mapsto w_{2n} \bar{g}^t w_{2n}^{-1},$$

where w_{2n} is the representative given by a permutation matrix of longest Weyl elements of GL_{2n} . When n is understood, we will abbreviate τ_n by τ . Note that τ_n stabilizes S_n and ψ_n . Throughout B_n will denote the Borel subgroup of GL_n and W_n the Weyl group of GL_n .

Lemma 3.1. *Let A be either a finite field or a p -adic field or a quaternion division algebra D over \mathcal{F} . For each $g \in \text{GL}_{2n}(A)$, there exist $s, s' \in S_n$ (depending on g) such that one of the following conditions holds:²*

(C. 1): $sgs'^{-1} = g$, and $\psi_n(ss'^{-1}) \neq 1$.

(C. 2): $sgs'^{-1} = g^\tau$, and $\psi_n(ss'^{-1}) = 1$.

Proof. We proceed the proof by Mathematical Induction. By Bruhat decomposition

$$\text{GL}_2 = B_2 W_2 B_2 = S_2 D W_2 D S_2, \text{ where } D = \left\{ \begin{pmatrix} a & \\ & 1 \end{pmatrix} \mid a \in A^* \right\}.$$

²If g satisfies **(C. 1)** (resp. **(C. 2)**), then g^τ , g^{-1} and $tg't'$, $t, t' \in S_n$ will also satisfy the same condition (with different s, s' .)

and $d_2(\beta) = \begin{pmatrix} I_n & \\ & \beta \end{pmatrix}$. Then the representatives of $S_n \backslash \text{GL}_{2n} / S_n$ can be expressed by

$$\{d_1(\alpha)\sigma_k d_2(\beta) | k = 0, \dots, n, \alpha, \beta \in \text{GL}_n\}.$$

For $k \in \{0, \dots, n\}$, fix any

$$\gamma_k = \gamma_k(\alpha, \beta) = d_1(\alpha)\sigma_k d_2(\beta) \in S_n \backslash \text{GL}_{2n} / S_n, \alpha, \beta \in \text{GL}_n.$$

Let $u_k = u_k(X) = \begin{pmatrix} I_n & X \\ & I_n \end{pmatrix}$, where $X = \begin{pmatrix} 0 & 0 \\ X_k & 0 \end{pmatrix}$, $X_k \in \text{Mat}_{n-k}$. Then $\sigma_k^{-1}u_k\sigma_k = u_k$. Let

$$n_1 = d_1(\alpha)u_k d_1(\alpha)^{-1} \in U_n \text{ and } n_2 = \gamma_k^{-1}n_1\gamma_k = d_2(\beta)^{-1}u_k d_2(\beta) \in U_n.$$

Note that

$$\psi_n(n_1) = \psi_0(\text{tr}(\alpha X)) \text{ and } \psi_n(n_2) = \psi_0(\text{tr}(X\beta)) = \psi_0(\text{tr}(\beta X)).$$

Denote $\alpha = \begin{pmatrix} * & \alpha_k \\ * & * \end{pmatrix}$, and $\beta = \begin{pmatrix} * & \beta_k \\ * & * \end{pmatrix}$, where $\alpha_k, \beta_k \in \text{Mat}_{n-k}$. Then

$$\alpha X = \begin{pmatrix} \alpha_k X_k & 0 \\ * & 0 \end{pmatrix}, \text{ and } \text{tr}(\alpha X) = \text{tr}(\alpha_k X_k).$$

Similarly, $\text{tr}(\beta X) = \text{tr}(\beta_k X_k)$. If $\alpha_k \neq \beta_k$, then there exists $X \in \text{Mat}_n$ such that $\psi_n(\text{tr}(\alpha X)) \neq \psi_n(\text{tr}(\beta X))$. Therefore condition **(C. 1)** holds for $\gamma_k = \gamma_k(\alpha, \beta)$ with $\alpha_k \neq \beta_k$.

Assume that $\alpha_k = \beta_k$. That is

$$\gamma_k = \begin{pmatrix} * & \alpha_k \\ * & * \\ & & I_n \end{pmatrix} \sigma_k \begin{pmatrix} I_n & & \\ & * & \alpha_k \\ & * & * \end{pmatrix} = \begin{pmatrix} \alpha_k & * \\ * & * \\ & & * & \alpha_k \\ & & & & w_k \end{pmatrix}.$$

Define an equivalence relation “ \sim ” on $g, g' \in \text{GL}_{2n}$, where $g \sim g'$ means that $sgs' = g'$ for some $s, s' \in S_n$. We sometimes use subscripts $\sim_{(s, s')}$ to indicate the connecting map (s, s') .

If $\text{rank}(\alpha_K) \neq 0$, there exist $g, h \in \text{GL}_{n-k}$ such that

$$\gamma_k \sim \begin{pmatrix} g & & & \\ & I_{n+k} & & \\ & & g & \\ & & & I_{n+k} \end{pmatrix} \gamma_k \begin{pmatrix} I_{n+k} & & & \\ & h & & \\ & & I_{n+k} & \\ & & & h \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 & * & * & * \\ \delta_{k-1} & 0 & * & * & * \\ * & * & * & * & * \\ & & * & 0 & 1 \\ & & * & \delta_{k-1} & 0 \\ w_k & & & & \end{pmatrix}, \text{ for some } \delta_{k-1} \in \text{Mat}_{n-k-1}.$$

For some suitable $m, m' \in M_n, u, u' \in U_n$

$$\begin{aligned} \gamma_k &\sim_{(m,m')} \begin{pmatrix} * & 0 & 1 & * & * & * \\ & \delta'_{k-1} & 0 & * & * & * \\ & * & 0 & * & * & * \\ & & & 0 & 0 & 1 \\ & & & * & \delta'_{k-1} & 0 \\ w_k & & & & & * \end{pmatrix} \\ &\sim_{(u,u')} \begin{pmatrix} 0 & 1 & & & & \\ \delta''_{k-1} & 0 & * & * & & \\ * & 0 & * & * & & \\ & & 0 & 0 & 1 & \\ & & * & \delta''_{k-1} & 0 & \\ w_k & & & & & \end{pmatrix} = \tilde{\gamma}_k. \end{aligned}$$

Let $N = \begin{pmatrix} N_1 & N_2 \\ N_3 & N_4 \end{pmatrix} \in \text{GL}_{2n-2}, N_i \in \text{Mat}_{n-1}$ be embedded in GL_{2n} as $\begin{pmatrix} & & 1 & & & \\ N_1 & & & N_2 & & \\ & & & & 1 & \\ N_3 & & & N_4 & & \end{pmatrix}$. By induction assumption, there exist

$$s = \begin{pmatrix} 1 & & & & & \\ & q & & Y & & \\ & & 1 & & & \\ & & & & q & \end{pmatrix} \text{ and } s' = \begin{pmatrix} p & & Z & & & \\ & 1 & & & & \\ & & p & & & \\ & & & & & 1 \end{pmatrix},$$

where $p, q \in \text{GL}_{n-1}, Y, Z \in \text{Mat}_{n-1}$ such that either **(C. 1)** or **(C. 2)** holds for $\tilde{\gamma}_k$. Note that the above embedding is consistent between (τ_{n-1}, ψ_{n-1}) and (τ_n, ψ_n) .

Now it suffices to show that **(C. 1)** or **(C. 2)** holds for those γ_k in the

form of

$$\gamma_k = \begin{pmatrix} & 0_{n-k} & * & * \\ & * & * & * \\ & & * & 0_{n-k} \\ w_k & & & \end{pmatrix}.$$

In this case, $k \geq n - k$ and assume $k = e + n - k$ for some non-negative integer e . Then for suitable

$$s_1 = \begin{pmatrix} v_{n-k} & & & \\ & v'_k & & \\ & & v_{n-k} & \\ & & & v'_k \end{pmatrix}, s_2 = \begin{pmatrix} r_k & & & \\ & r'_{n-k} & & \\ & & r_k & \\ & & & r'_{n-k} \end{pmatrix} \in M_n$$

$u, u' \in U_n$; $v'_k, r_k \in \text{Mat}_k$; $v_{n-k}, r'_{n-k} \in \text{Mat}_{n-k}$, we can reduce γ_k to

$$\gamma_k \sim_{(s_1, s_2)} \begin{pmatrix} 0 & * & * \\ I_{n-k} & * & * \\ & I_{n-k} & 0 \\ \lambda_k & & \end{pmatrix} \sim_{(u, u')} \begin{pmatrix} 0 & 0 & \eta_k \\ I_{n-k} & 0 & 0 \\ & I_{n-k} & 0 \\ \lambda_k & & \end{pmatrix} = \gamma'_k,$$

for some $\lambda_k, \eta_k \in \text{Mat}_k$.

Denote

$$\lambda_k = \begin{pmatrix} \lambda_{e, n-k}^1 & \lambda_{e, e}^2 \\ \lambda_{n-k, n-k}^3 & \lambda_{n-k, e}^4 \end{pmatrix}; \eta_k = \begin{pmatrix} \eta_{n-k, e}^1 & \eta_{n-k, n-k}^2 \\ \eta_{e, e}^3 & \eta_{e, n-k}^4 \end{pmatrix};$$

$$C = \begin{pmatrix} C_{e, n-k}^1 & C_{e, e}^2 \\ C_{n-k, n-k}^3 & C_{n-k, e}^4 \end{pmatrix} = \eta_k^{-1}; \text{ and } D = \begin{pmatrix} D_{n-k, e}^1 & D_{n-k, n-k}^2 \\ D_{e, e}^3 & D_{e, n-k}^4 \end{pmatrix} = \lambda_k^{-1},$$

where subscripts denote the sizes of matrices. Let

$$s_3 = \begin{pmatrix} I_{n-k} & & Y^1 & & & \\ & g^1 & I_e & & Y^2 & \\ & g^2 & g^3 & I_{n-k} & Y^3 & Y^4 \\ & & & & I_{n-k} & \\ & & & & g^1 & I_e \\ & & & & g^2 & g^3 & I_{n-k} \end{pmatrix} \in S_n,$$

and $s_4 = \gamma'_k s_3 (\gamma'_k)^{-1} =$

$$\begin{pmatrix} \eta^2 g^3 C^1 + I_{n-k} & \eta^2 g^3 C^2 & 0 & \eta^1 g^1 + \eta^2 g^2 & & \\ \eta^4 g^3 C^1 & \eta^4 g^3 C^2 + I_e & 0 & \eta^3 g^1 + \eta^4 g^2 & & \\ Y^3 C^1 + Y^4 C^3 & Y^3 C^2 + Y^4 C^4 & I_{n-k} & 0 & g^2 D^1 + g^3 D^3 & g^2 D^2 + g^3 D^4 \\ & & & I_{n-k} & 0 & 0 \\ & & & \lambda^1 Y^1 + \lambda^2 Y^2 & \lambda^2 g^1 D^1 + I_e & \lambda^2 g^1 D^2 \\ & & & \lambda^3 Y^1 + \lambda^4 Y^2 & \lambda^4 g^1 D^1 & \lambda^4 g^1 D^2 + I_{n-k} \end{pmatrix}.$$

Therefore $s_4 \in S_n$ if and only if

$$\begin{cases} \eta^2 g^3 C^1 = \eta^2 g^3 C^2 = \lambda^2 g^1 D^2 = \lambda^4 g^1 D^2 = 0 \\ \eta^4 g^3 C^2 = \lambda^2 g^1 D^1 \\ \lambda^1 Y^1 + \lambda^2 Y^2 = \eta^4 g^3 C^1 \\ \lambda^3 Y^1 + \lambda^4 Y^2 = Y^3 C^1 + Y^4 C^3 (= p, \text{ say }) \\ Y^3 C^2 + Y^4 C^4 = \lambda^4 g^1 D^1 \end{cases}. \quad (3.1)$$

Note that the last three equations in the system are equivalent to

$$\lambda_k \begin{pmatrix} Y^1 \\ Y^2 \end{pmatrix} = \begin{pmatrix} \eta^4 g^3 C^1 \\ p \end{pmatrix}, (Y^3, Y^4) \eta_k^{-1} = (p, \lambda^4 g^1 D^1). \quad (3.2)$$

$$(\text{Or } \begin{pmatrix} Y^1 \\ Y^2 \end{pmatrix} = \lambda_k^{-1} \begin{pmatrix} \eta^4 g^3 C^1 \\ p \end{pmatrix}, (Y^3, Y^4) = (p, \lambda^4 g^1 D^1) \eta_k.)$$

Also,

$$\begin{aligned} \psi_n(s_3) &= \psi_0(\text{tr}(Y^1 + Y^4)) = \psi_0(\text{tr}(D^1 \eta^4 g^3 C^1 + D^2 p + p \eta^2 + \lambda^4 g^1 D^1 \eta^4)), \\ &= \psi_0(\text{tr}(p(D^2 + \eta^2) + D^1 \eta^4 g^3 C^1 + \lambda^4 g^1 D^1 \eta^4)) \end{aligned}$$

$$\psi_n(s_4) = \psi_0(\text{tr}(\eta^1 g^1 + \eta^2 g^2 + g^2 D^2 + g^3 D^4)) = \psi_0(\text{tr}(g^2(D^2 + \eta^2) + \eta^1 g^1 + g^3 D^4)).$$

If we let $g^1 = g^3 = 0$ and chose $Y^i, i = 1, 2, 3, 4$ such that

$$Y^3 C^2 + Y^4 C^4 = 0, Y^1 = D^2(Y^3 C^1 + Y^4 C^3), Y^2 = D^4(Y^3 C^1 + Y^4 C^3).$$

Then $s_4 \in S_n$ and

$$\psi_n(s_3) = \psi_0(\text{tr}(p(D^2 + \eta^2))) = \psi_0(\text{tr}(Y^3 C^1 + Y^4 C^3)(D^2 + \eta^2)),$$

$$\psi_n(s_4) = \psi_0(\text{tr}(\eta^2 g^2 + g^2 D^2)) = \psi_0(\text{tr}(g^2(D^2 + \eta^2))).$$

If $\eta^2 \neq -D^2$, we can choose suitable g^2 such that $\psi_n(s_3) \neq \psi_n(s_4)$. In this case, γ'_k satisfies **(C. 1)** and so does γ_k .

Suppose that $\eta^2 = -D^2$ in γ_k and the rank of η^2 equals n' . Choose $g, h \in \text{Mat}_{n-k}$ such that $g\eta^2 h = \begin{pmatrix} 0 & -I_{n'} \\ 0 & 0 \end{pmatrix}$ and let

$$m = \text{diag}(g, I_e, h^{-1}), m' = \text{diag}(g^{-1}, I_e, h).$$

Then γ'_k

$$\sim_{(m, m')} \begin{pmatrix} 0 & 0 & \begin{pmatrix} * & * & 0 & -I_{n'} \\ * & * & 0 & 0 \\ * & * & * & * \\ * & * & * & * \end{pmatrix} \\ I_{n-k} & 0 & 0 \\ \lambda'_k & I_{n-k} & 0 \end{pmatrix} \sim \begin{pmatrix} 0 & 0 & \tilde{\eta}_k \\ * & I_{n-k} & 0 \\ \lambda''_k & I_{n-k} & * \end{pmatrix},$$

where $\tilde{\eta}_k = \begin{pmatrix} 0 & 0 & 0 & -I_{n'} \\ 0 & I_{n''} & 0 & 0 \\ 0 & 0 & I_{n''} & 0 \\ I_{2k-n-n''} & 0 & 0 & 0 \end{pmatrix}$, and $n'' = n - k - n'$. For suitable $u, u' \in U_n$, further reduction shows that

$$\gamma_k \sim_{(u, u')} \begin{pmatrix} 0 & 0 & \tilde{\eta}_k \\ I_{n-k} & 0 & 0 \\ \tilde{\lambda}_k & I_{n-k} & 0 \end{pmatrix} = \tilde{\gamma}_k.$$

Next we consider

$$\tilde{\gamma}_k^{-1} = \begin{pmatrix} 0 & 0 & \tilde{\lambda}_k^{-1} \\ I_{n-k} & 0 & 0 \\ \tilde{\eta}_k^{-1} & I_{n-k} & 0 \end{pmatrix}.$$

By the same argument and the equality of η^2 and $-D^2$, we may assume that

$$\tilde{\lambda}_k^{-1} = \begin{pmatrix} 0 & 0 & I_{n'} \\ B_{n-k, 2k-n}^1 & 0 & 0 \\ B_{2k-n, 2k-n}^3 & B_{2k-n, n''}^4 & 0 \end{pmatrix},$$

where subscripts denote the sizes of matrices.

Now it suffices to show that

$$\theta_k = \begin{pmatrix} 0 & 0 & \tilde{\eta}_k \\ I_{n-k} & 0 & 0 \\ \tilde{\lambda}_k & I_{n-k} & 0 \end{pmatrix} \text{ with } \tilde{\eta}_k = \begin{pmatrix} 0 & 0 & I_{n'} \\ B_{n-k, 2k-n}^1 & 0 & 0 \\ B_{2k-n, 2k-n}^3 & B_{2k-n, n''}^4 & 0 \end{pmatrix}$$

and $\tilde{\lambda}_k = \begin{pmatrix} 0 & 0 & 0 & -I_{n'} \\ 0 & I_{n''} & 0 & 0 \\ 0 & 0 & I_{n''} & 0 \\ I_{2k-n-n''} & 0 & 0 & 0 \end{pmatrix}$ satisfies one of the conditions **(C. 1)**

or **(C. 2)**. Consider the system (3.1) for θ_k . Take

$$g^1 = \begin{pmatrix} 0 & r_{n'', n''} \\ 0 & 0 \end{pmatrix}, g^3 = \begin{pmatrix} *_{n'', 2k-n} \\ 0 \end{pmatrix}, \quad (3.3)$$

where subscripts denote the sizes of matrices. Then

$$\eta^2 g^3 = 0, g^1 D^2 = 0, \eta^4 g^3 C^2 = 0, \lambda^2 g^1 D^1 = 0$$

and $s_4 \in S_n$ with some suitable Y^i satisfying equation (3.2). Unless $D^1\eta^4\lambda^4g^1 = \eta^1g^1$ and $g^3C^1D^1\eta^4 = g^3D^4$ for all g^1, g^3 in the form of equation (3.3), there exist $s_3, s_4 \in S_n$ such that **(C. 1)** holds for θ_k . (Note that $tr\lambda^4g^1D^1\eta^4 = trD^1\eta^4\lambda^4g^1$, etc..)

Next we consider those θ_k satisfying:

$$\text{Condition (3.4) : } D^1\eta^4\lambda^4g^1 = \eta^1g^1 \text{ and } g^3C^1D^1\eta^4 = g^3D^4$$

for all g^1, g^3 in the form of equation (3.3).

Let $\eta^4 = \begin{pmatrix} T^1 & 0 \\ T^2 & 0 \end{pmatrix}$; $\eta^1 = \begin{pmatrix} 0 & 0 \\ T^3 & T^4 \end{pmatrix}$; and $C^1 = \begin{pmatrix} 0 & V^1 \\ 0 & V^2 \end{pmatrix}$, where $T^2, T^3, V^1 \in \text{Mat}_{n''}$. Then

$$\begin{aligned} D^1\eta^4\lambda^4g^1 &= \begin{pmatrix} 0 & 0 \\ 0 & I_{n''} \end{pmatrix} \begin{pmatrix} T^1 & 0 \\ T^2 & 0 \end{pmatrix} \begin{pmatrix} I_{n''} & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & r_{n'',n''} \\ 0 & 0 \end{pmatrix} \\ &= \begin{pmatrix} 0 & 0 \\ 0 & T^2r_{n'',n''} \end{pmatrix} \\ \eta^1g^1 &= \begin{pmatrix} 0 & 0 \\ T^3 & T^4 \end{pmatrix} \begin{pmatrix} 0 & r_{n'',n''} \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & T^3r_{n'',n''} \end{pmatrix}; \\ g^3C^1D^1\eta^4 &= \begin{pmatrix} *_{n'',2k-n} \\ 0 \end{pmatrix} \begin{pmatrix} 0 & V^1 \\ 0 & V^2 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & I_{n''} \end{pmatrix} \begin{pmatrix} T^1 & 0 \\ T^2 & 0 \end{pmatrix} \\ &= \begin{pmatrix} *_{n'',2k-n} \\ 0 \end{pmatrix} \begin{pmatrix} V^1T^2 & 0 \\ V^2T^2 & 0 \end{pmatrix} \\ g^3D^4 &= \begin{pmatrix} *_{n'',2k-n} \\ 0 \end{pmatrix} \begin{pmatrix} I_{n''} & 0 \\ 0 & 0 \end{pmatrix}. \end{aligned}$$

Condition (3.4) implies that

$$T^2 = T^3, V^1T^2 = I_{n''}, V^2 = 0.$$

That is

$$\theta_k = \begin{pmatrix} 0 & 0 & \tilde{\eta}_k \\ I_{n-k} & 0 & 0 \\ \tilde{\lambda}_k & I_{n-k} & 0 \end{pmatrix},$$

with $\tilde{\eta}_k = \begin{pmatrix} 0 & 0 & 0 & I_{n'} \\ T^2 & T^4 & 0 & 0 \\ * & * & T^1 & 0 \\ * & * & T^2 & 0 \end{pmatrix}$, $\tilde{\lambda}_k = \begin{pmatrix} 0 & 0 & 0 & I_{2k-n'-n''} \\ 0 & I_{n''} & 0 & 0 \\ 0 & 0 & I_{n''} & 0 \\ -I_{n'} & 0 & 0 & 0 \end{pmatrix}$. Since $V^1 T^2 = I_{n''}$ implies that $\det T^2 \neq 0$,

$$\theta_k \sim \begin{pmatrix} & & & \begin{pmatrix} 0 & 0 & 0 & I_{n'} \\ T^2 & 0 & 0 & 0 \\ & E & 0 & 0 \\ & & T^2 & 0 \end{pmatrix} \\ & I_{n-k} & & \\ & & I_{n-k} & \\ \begin{pmatrix} 0 & 0 & 0 & I_{2k-n'-n''} \\ 0 & I_{n''} & 0 & 0 \\ 0 & 0 & I_{n''} & 0 \\ -I_{n'} & 0 & 0 & 0 \end{pmatrix} & & & \end{pmatrix},$$

for some $E \in \mathrm{GL}_{2k-n-2n''}$. In the case of fields, there exists some $g \in \mathrm{GL}_{2k-n-2n''}$ such that $gEg^{-1} = E^t$, where E^t denotes the transpose of E . In the case of quaternion division algebras, there exists some $g \in \mathrm{GL}_{2k-n-2n''}$ such that $gEg^{-1} = \bar{E}^t$ (cf. [Ra], Lemma 3.1). In either case, there exists $g \in \mathrm{GL}_{2k-n-2n''}$ such that $gEg^{-1} = E^\tau$. Let

$$\zeta = \mathrm{diag}(I_{n'+n''}, g, I_{n-k+2n''}, I_{n'+n''}, g, I_{n-k+2n''}).$$

Then $\zeta \theta_k \zeta^{-1} = \theta_k^\tau$ and θ_k satisfies **(C. 2)**. □

Theorem 3.2. *For any $n \in \mathbb{N}$, let $G = \mathrm{GL}_{2n}(\mathbb{F}_q)$, where \mathbb{F}_q is a finite field. Then*

$$\dim \mathrm{Hom}_G(\rho, \mathrm{Ind}_{S_n}^G \psi_n) \leq 1,$$

for any irreducible representation of G .

Proof. Let $\pi = \mathrm{Ind}_{S_n}^G \psi_n$. Lemma 3.1 implies that elements

$$\Delta : G \mapsto \mathrm{Hom}_{\mathbb{C}}(\mathrm{Ind}_{S_n}^G \psi_n, \mathrm{Ind}_{S_n}^G \psi_n)$$

satisfying

$$\Delta(s'gs) = \pi(s') \circ \Delta(g) \circ \pi(s), \text{ for } s, s' \in S_n$$

is τ -invariant. By Theorem 2.1 $\mathrm{Hom}_G(\mathrm{Ind}_{S_n}^G \psi_n, \mathrm{Ind}_{S_n}^G \psi_n)$ is abelian and the result follows. □

Lemma 3.3. *Let G denote $\mathrm{GL}_{2n}(A)$, where A is a p -adic field \mathcal{F} or a quaternion division algebra D over \mathcal{F} . If T is a distribution on G satisfying*

$$T(L_{h_1} \circ R_{h_2}(\eta)) = \psi_n(h_1 h_2^{-1})T(\eta) \text{ for } h_1, h_2 \in \mathrm{S}_n(A), \eta \in C_c^\infty(G), \quad (3.4)$$

then T is τ -invariant.

Proof. ³ Let \mathbb{H} denote $\mathrm{S}_n(A)$. We verify the assumptions of Theorem 6.10 in [BZ1]. Put $\hat{\mathbb{H}} = \mathbb{H} \times \mathbb{H}$. Let $(h_1, h_2) \in \hat{\mathbb{H}}$ act on $g \in G$ and $\eta \in C_c^\infty(G)$ by

$$(h_1, h_2) \cdot g = h_1 g h_2^{-1} \text{ and } (h_1, h_2) \cdot \eta(g) = \psi_n(h_1^{-1} h_2) \eta(h_1^{-1} g h_2).$$

The assumptions of Theorem 6.10 in [BZ1] in this case are the following:

1. *The action of $\hat{\mathbb{H}}$ is constructible (same as constructive in the sense of [BZ1]), which means that the set of $\{(g, \hat{h} \cdot g) | g \in G, \hat{h} \in \hat{\mathbb{H}}\}$ is the union of finitely many locally closed subsets of $G \times G$.*
2. *For each $\hat{h} \in \hat{\mathbb{H}}$, there is $\hat{h}_\tau \in \hat{\mathbb{H}}$ such that $\hat{h} \cdot g^\tau = (\hat{h}_\tau \cdot g)^\tau$ for all $g \in G$.*
3. $\tau^2 = \mathrm{id}$.
4. *If T is a nonzero $\hat{\mathbb{H}}$ -invariant distribution on an $\hat{\mathbb{H}}$ -orbit Y , then $Y^\tau = Y$ and $T^\tau = T$.*

The conclusion is that any $\hat{\mathbb{H}}$ -invariant distribution on G is also τ -invariant.

By Theorem A in 6.15 of [BZ1] the action of $\hat{\mathbb{H}}$ is constructable on $\mathrm{GL}_{2n}(\mathcal{F})$. Also $\iota \hat{\mathbb{H}}$ is constructable on $\mathrm{GL}_{4n}(K)$, $K = \mathcal{F}(\sqrt{\alpha})$ and its closed subgroup $\mathrm{GL}_{2n}(D)$, where ι is the embedding defined earlier. The condition 1 is then verified. For condition 2, take $\hat{h}_\tau = (h_2^{-\tau}, h_1^{-\tau})$ for $\hat{h} = (h_1, h_2) \in \hat{\mathbb{H}}$. Since \mathbb{H} is τ -invariant and $(\hat{h}_\tau)_\tau = \hat{h}$, τ induces an anti-involution on $\hat{\mathbb{H}}$ (still denoted by τ)

$$\tau : \hat{\mathbb{H}} \mapsto \hat{\mathbb{H}} \text{ by } \hat{h} \mapsto \hat{h}_\tau.$$

The action of $\hat{h} \in \hat{\mathbb{H}}$ satisfies that $\hat{h} \cdot g^\tau = (\hat{h}_\tau \cdot g)^\tau$ for all $g \in G$. Condition 3 is obvious. To verify condition 4, let T be a nonzero $\hat{\mathbb{H}}$ -invariant distribution on an $\hat{\mathbb{H}}$ -orbit $Y = \mathbb{H}g\mathbb{H}$, i.e.

$$T(\hat{h} \cdot (\eta)) = T(\eta) \text{ for all } \hat{h} = (h_1, h_2) \in \hat{\mathbb{H}} \text{ and } \eta \in C_c^\infty(Y).$$

³This proof mimics Theorem 2.3 [So]. We keep it here for the sake of completion.

Denote by $\hat{\mathbb{H}}_g$ the stabilizer of g in $\hat{\mathbb{H}}$. Then $Y \cong \hat{\mathbb{H}}/\hat{\mathbb{H}}_g$. Define a character $\hat{\psi}_n$ of $\hat{\mathbb{H}}$ by:

$$\hat{\psi}_n(\hat{h}) = \psi_n(h_1 h_2^{-1}) \text{ for } \hat{h} = (h_1, h_2) \in \hat{\mathbb{H}},$$

then $\hat{\psi}_n$ is τ -invariant and $C_c^\infty(Y) \cong \text{ind}_{\hat{\mathbb{H}}_g}^{\hat{\mathbb{H}}} 1$ (un-normalized compact induction). We have that

$$T \in \text{Hom}_{\hat{\mathbb{H}}}(\text{ind}_{\hat{\mathbb{H}}_g}^{\hat{\mathbb{H}}} 1, \hat{\psi}_n) \cong \text{Hom}_{\hat{\mathbb{H}}_g}(\delta_{\hat{\mathbb{H}}} \delta_{\hat{\mathbb{H}}_g}^{-1}, \text{Res}_{\hat{\mathbb{H}}_g} \hat{\psi}_n)$$

by Frobenius reciprocity, where $\delta_{\hat{\mathbb{H}}}$, $\delta_{\hat{\mathbb{H}}_g}$ are the modular functions of $\hat{\mathbb{H}}$ and $\hat{\mathbb{H}}_g$ respectively. Since $|\hat{\psi}_n| \equiv 1$ and $\delta_{\hat{\mathbb{H}}} \delta_{\hat{\mathbb{H}}_g}^{-1}$ is positive, by Schur's lemma we have

$$\text{either } \dim \text{Hom}_{\hat{\mathbb{H}}_g}(\delta_{\hat{\mathbb{H}}} \delta_{\hat{\mathbb{H}}_g}^{-1}, \text{Res}_{\hat{\mathbb{H}}_g} \hat{\psi}_n) = 0 \text{ or } \delta_{\hat{\mathbb{H}}} \delta_{\hat{\mathbb{H}}_g}^{-1} = \text{Res}_{\hat{\mathbb{H}}_g} \hat{\psi}_n \equiv 1.$$

Therefore we conclude that: $\text{Hom}_{\hat{\mathbb{H}}_g}(\delta_{\hat{\mathbb{H}}} \delta_{\hat{\mathbb{H}}_g}^{-1}, \text{Res}_{\hat{\mathbb{H}}_g} \hat{\psi}_n) = 0$ for those g satisfy **(C. 1)**, i.e. there is no nontrivial $\hat{\mathbb{H}}$ -invariant distribution T on such Y .

Now we consider those g satisfies **(C. 2)**, i.e.

$$\hat{k} \cdot g = g^\tau \text{ for some } \hat{k} = (k_1, k_2) \in \hat{\mathbb{H}} \text{ with } \hat{\psi}_n(\hat{k}) = 1.$$

We may assume that $\delta_{\hat{\mathbb{H}}} \delta_{\hat{\mathbb{H}}_g}^{-1} \equiv 1$, since otherwise $\hat{\mathbb{H}}$ -invariant distribution on such Y is trivial. Note that $\hat{k} \cdot g = g^\tau$ implies the double coset $Y = \mathbb{H}g\mathbb{H}$ is τ -invariant. It remains to show that $T^\tau = T$. In our case T is proportional (see 6.12 of [BZ1]) to

$$T_1(\eta) = \int_{\hat{\mathbb{H}}/\hat{\mathbb{H}}_g} \eta(\hat{h} \cdot g) \hat{\psi}_n^{-1}(\hat{h}) d\hat{h},$$

where $d\hat{h}$ is a left $\hat{\mathbb{H}}$ -invariant measure on $\hat{\mathbb{H}}/\hat{\mathbb{H}}_g$. We have

$$\begin{aligned} T_1^\tau(\eta) &= T_1(\eta^\tau) = \int_{\hat{\mathbb{H}}/\hat{\mathbb{H}}_g} \eta((\hat{h} \cdot g)^\tau) \hat{\psi}_n^{-1}(\hat{h}) d\hat{h} \\ &= \int_{\hat{\mathbb{H}}/\hat{\mathbb{H}}_g} \eta(\hat{h}_\tau \cdot g^\tau) \hat{\psi}_n^{-1}(\hat{h}) d\hat{h} \end{aligned}$$

$$= \int_{\hat{\mathbb{H}}/\hat{\mathbb{H}}_g} \eta(\hat{h}_\tau \cdot \hat{k} \cdot g) \hat{\psi}_n^{-1}(\hat{h}) d\hat{h} = \int_{\hat{\mathbb{H}}/\hat{\mathbb{H}}_g} \eta(\hat{h}' \cdot g) \hat{\psi}_n^{-1}(\hat{h}') \hat{\psi}_n(\hat{k}) d\hat{h}'.$$

Last equality is obtained by change of variables $\hat{h}' = \hat{h}_\tau \cdot \hat{k}$ along with our assumption that $\delta_{\hat{\mathbb{H}}} \delta_{\hat{\mathbb{H}}_g}^{-1} \equiv 1$ and the fact that $\hat{\psi}_n$ is τ -invariant. Since $\hat{\psi}_n(\hat{k}) = 1$, we have

$$T_1^\tau(\eta) = \int_{\hat{\mathbb{H}}/\hat{\mathbb{H}}_g} \eta(\hat{h}' \cdot g) \hat{\psi}_n^{-1}(\hat{h}') d\hat{h}' = T_1(\eta).$$

□

Theorem 3.4. *Let $G = \mathrm{GL}_{2n}(A)$, where A is either a p -adic field \mathcal{F} or a quaternion division algebra D over \mathcal{F} . Then $\dim \mathrm{Hom}_G(\rho, \mathrm{Ind}_{\mathbb{S}_n}^G \psi_n) \leq 1$, for any irreducible representation ρ of G .*

Proof. We have obtained

$$\dim \mathrm{Hom}_G(\pi; \mathrm{Ind}_{\mathbb{S}_n}^G \psi_n) \cdot \dim \mathrm{Hom}_{\mathbb{S}_n}(\mathrm{Res}_{\mathbb{S}_n}^G \tilde{\pi}; \psi_n) \leq 1,$$

for any irreducible representation π of G from the previous theorem and the Gelfand-Kazhdan criterion. It suffices to show that if π has a nontrivial Shalika functional then $\tilde{\pi}$ will also have one. Assume that Λ_π is a nontrivial Shalika functional for π , i.e.

$$\Lambda_\pi(\pi(h)v) = \psi_n(h) \Lambda_\pi(v) \text{ for all } h \in \mathbb{S}_n \text{ and } v \in V_\pi.$$

Define a representation π' on the same vector space V_π by

$$\pi'(g)v = \pi(\xi g^{-\tau} \xi^{-1})v,$$

where $\xi = \mathrm{diag}(I_n, -I_n)$. Then $\psi(\xi s^{-\tau} \xi^{-1}) = \psi(s)$ for $s \in \mathbb{S}_n$, and Λ_π is also a Shalika functional for π' .

In the case of \mathcal{F} , define another representation π'' on the same vector space V_π by

$$\pi''(g)v = \pi(g^{-t})v.$$

Then $\pi'' \cong \tilde{\pi}$ by Theorem 7.3 in [BZ1]. Since $\xi g^{-\tau} \xi^{-1}$ is conjugate to g^{-t} , we have $\pi' \cong \tilde{\pi}$.

In the case of D , define another representation π'' on the same vector space V_π by

$$\pi''(g)v = \pi(\eta \bar{g}^{-t} \eta^{-1})v,$$

where $\eta(i, j) = (-1)^i \delta_{i, 2n-j+1}$. Then $\pi'' \sim \tilde{\pi}$ by Theorem 3.1 [Ra]. Since $\xi g^{-\tau} \xi^{-1}$ is conjugate to $\eta \bar{g}^{-t} \eta^{-1}$, we have $\pi' \sim \pi'' \sim \tilde{\pi}$.

In either case,

$$\begin{aligned} \dim \operatorname{Hom}_G(\tilde{\pi}; \operatorname{Ind}_{S_n}^G \psi_n) &= \dim \operatorname{Hom}_G(\pi'; \operatorname{Ind}_{S_n}^G \psi_n) \\ &= \dim \operatorname{Hom}_{S_n}(\pi'|_{S_n}; \psi_n) \geq 1, \end{aligned}$$

which completes the proof. \square

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- Chufeng Nien, nienpig@mail.ncku.edu.tw, Department of Mathematics, National Cheng Kung University, Tainan 701, TAIWAN