

IX. Systems of Linear Equations

(1)

$m \times n$ system of linear equations is a collection of m linear equations w/ n -unknowns

$$\textcircled{*} \begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases}$$

In matrix form

coefficient matrix $\rightarrow A = (a_{ij}) \in \text{Mat}_{m \times n}$; $1 \leq i \leq m$, $1 \leq j \leq n$

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n$$
$$b = \begin{pmatrix} b_1 \\ \vdots \\ b_m \end{pmatrix} \in \mathbb{R}^m$$

$\textcircled{*}$ may be re-written as

$$Ax = b.$$

the system is homogeneous (inhomogeneous) if $b=0$ ($b \neq 0$)

General Discussions:

1. $K_b := \{ u \in \mathbb{R}^n \mid Au = b \}$

= solution for $Ax = b$

K_b is a subspace $\Leftrightarrow b = 0$

$\Rightarrow K_b$ a subspace, $0 \in K_b \Rightarrow A \cdot \underset{0}{0} = b$ ✓

$\Leftarrow K_0 = \{ u \in \mathbb{R}^n \mid Au = 0 \} = N(A)$,
a subspace of \mathbb{R}^n ✓

and $\dim K_0 = n - \text{rank}(A)$

2. $0 \in K_0$, $\therefore \{0\} \subset K_0$. (2)

But if $\{0\} = K_0 \Rightarrow L_A$ is injective

If, in addition, that $n=m$, L_A is isomorphism.

L_A is isomorphism $\Leftrightarrow A \in \text{Mat}_{n \times n}$ and the only solution to $Ax=0$ is $x=0$.

3.

Number of solutions?

Thm, $Ax=b$ either has no solution, 1 solution, or infinitely many solutions.

Pf if $x \neq y$ both satisfy $Ax = Ay = b$,

then, $A(\lambda x + (1-\lambda)y)$

$$\forall \lambda \in \mathbb{R}, = A(\lambda x) + A((1-\lambda)y)$$

$$= \lambda A(x) + (1-\lambda)Ay$$

$$= \lambda b + (1-\lambda)b = b.$$

$\therefore \infty$ -many solutions.

QED,

Finding K_b : (solving $Ax=b$; $A \in \text{Mat}_{m \times n}$, $b \in \mathbb{R}^m$) (4)

• $m=n$ and A is invertible, $\Rightarrow x = A^{-1}b$
 $K_b = \{A^{-1}b\} = \{0\}$ if $b=0$

• If $B \in \text{Mat}_{m \times m}$ invertible

$$K_b = K'_{Bb}$$

where $K'_{Bb} = \{u \in \mathbb{R}^n \mid BAu = Bb\}$

since $BAx = Bb$

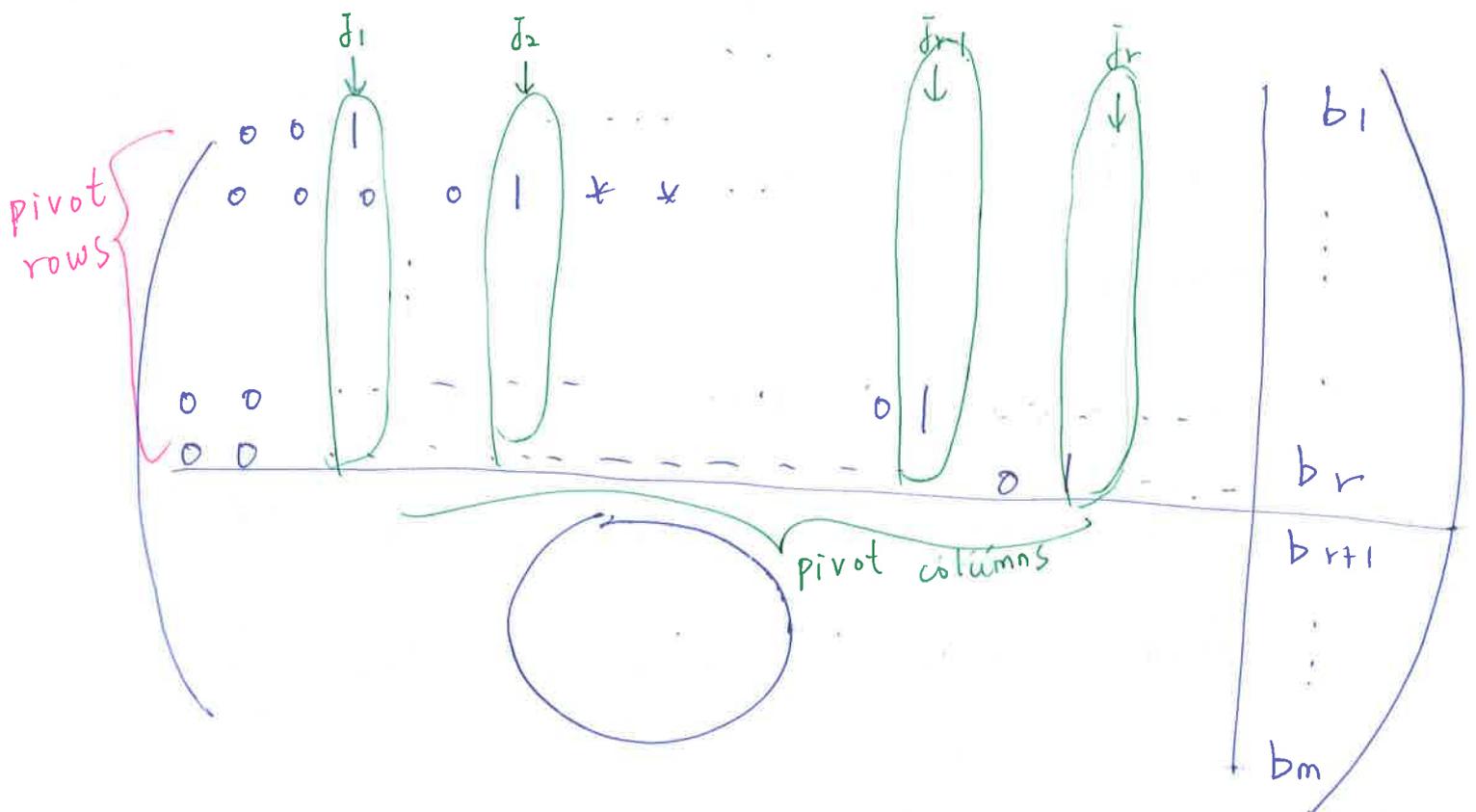
$$x \in K_b \Rightarrow Ax = b \Rightarrow BAx = Bb \Rightarrow x \in K'_{Bb}$$

$$x \in K'_{Bb} \Rightarrow BAx = Bb \Rightarrow B^{-1}(BAx) = B^{-1}(Bb)$$

$$\Rightarrow Ax = b \Rightarrow x \in K_b$$

let $(A|b) \in \text{Mat}_{m \times (n+1)}$ be the augmented matrix

K_b can be easily described if A is in rref:



if any $b_{r+1}, \dots, b_m \neq 0 \Rightarrow$ no solution

($\because 0x_1 + 0x_2 + \dots + 0x_n \neq 0$
'not possible')

system is called inconsistent.

$$K_b = \emptyset$$

egⁿ

$$\begin{cases} 2x + 4y = 2 & \dots \textcircled{1} \\ 4x + 8y = 7 & \dots \textcircled{2} \end{cases} \rightarrow \left(\begin{array}{cc|c} 2 & 4 & 2 \\ 4 & 8 & 7 \end{array} \right)$$

$$-2 \cdot \textcircled{1} + \textcircled{2}:$$

$$\begin{cases} 2x + 4y = 2 \\ 0x + 0y = 3 \end{cases} \leftrightarrow \left(\begin{array}{cc|c} 2 & 4 & 2 \\ 0 & 0 & 3 \end{array} \right) \text{ inconsistent.}$$

\therefore Suppose $Ax=b$ is consistent, ie $b_{r+1} = \dots = b_m = 0$.

Get r equations:

$$\left\{ \begin{aligned} & a_{1j_1} x_{j_1} + a_{1j_{r+1}} x_{j_{r+1}} + \dots + a_{1n} x_n = b_1 \\ & a_{2j_1} x_{j_1} + a_{2j_{r+1}} x_{j_{r+1}} + \dots + a_{2n} x_n = b_2 \\ & \vdots \\ & a_{rj_1} x_{j_1} + a_{rj_{r+1}} x_{j_{r+1}} + \dots + a_{rn} x_n = b_r \end{aligned} \right.$$

eg r : $x_{j_{r+1}}, \dots, x_n$ free and $x_{j_r} = b_r - \sum_{i=1}^{n-j_r} a_{r,j_r+i} x_{j_r+i}$

eg $r-1$: $x_{j_{r-1}+1}, \dots, \hat{x}_{j_r}, \dots, x_n$ free $x_{j_{r-1}} = b_{r-1} - \sum_{i=1}^{n-j_{r-1}} a_{r-1,j_{r-1}+i} x_{j_{r-1}+i}$

$$K_b = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_{j_1} \\ x_{j_1+1} \\ \vdots \\ x_{j_2} \\ x_{j_2+1} \\ \vdots \\ x_{j_r} \\ x_{j_r+1} \\ \vdots \\ x_r \end{pmatrix} \mid \begin{array}{l} \text{all } x_j \text{ free except } x_{j_i} \\ x_{j_i} \in \text{Sp } \{x_{j_i+1}, \dots, x_r\} \end{array} \right\} \quad (b)$$

If $b=0$, K_0 is a subspace of \mathbb{R}^n with dimension $n-r$. (since all x_j , except x_{j_1}, \dots, x_{j_r} are free)

eg¹¹

$$\begin{cases} 0x_1 + x_2 + 2x_3 + 2x_4 + x_5 = 1 \\ 0x_1 + 0x_2 + 0x_3 + x_4 + 2x_5 = 2 \\ 0x_1 + 0x_2 + 0x_3 + 0x_4 + x_5 = 3 \\ 0x_1 + 0x_2 + 0x_3 + 0x_4 + 0x_5 = 0 \\ 0x_1 + 0x_2 + 0x_3 + 0x_4 + 0x_5 = 0 \end{cases}$$

$$\begin{pmatrix} 0 & \overset{2}{\downarrow} & 2 & \overset{4}{\downarrow} & \overset{5}{\downarrow} & 1 \\ 0 & 0 & 0 & 1 & 2 & 2 \\ 0 & 0 & 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$x_5 = 3$$

$$x_4 + 2x_5 = 2 \Rightarrow x_4 = -4$$

$$x_2 + 2x_3 + 2x_4 + x_5 = 1 \Rightarrow x_2 = -2x_3 + 8 - 3 = 6 - 2x_3$$

x_1, x_3 free

$$K_b = \left\{ \begin{pmatrix} x_1 \\ 6 - 2x_3 \\ x_3 \\ -4 \\ 3 \end{pmatrix} \right\} = \left\{ \begin{pmatrix} 0 \\ 0 \\ 0 \\ -4 \\ 3 \end{pmatrix} + x_1 \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} 0 \\ -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$= \underbrace{\left\{ \begin{pmatrix} 0 \\ 0 \\ 0 \\ -4 \\ 3 \end{pmatrix} \right\}}_{\text{"SS"}} + \underbrace{\text{Sp} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\}}_{K_0}$$

(7)

For a general system $AX=b$, we row reduce A into $\text{rref}(A)$, i.e. apply series of row operations

$$E = E_1 \cdots E_p \quad \text{s.t.} \quad EA = \text{rref}(A)$$

In terms of augmented matrix:

$$E(A|b) = (EA|Eb) = (\text{rref}(A)|Eb)$$

Since E is invertible, $K_b = K'_{Eb}$ and we describe K_b by describing $K_{EA=Eb}$.

In particular, if $b=0$ (homogeneous system),

$$(A|0) = (EA|0)$$

null space of $A =$ null space of EA .

eg 11

$$\begin{cases} 3x_1 + 2x_2 + 3x_3 - 2x_4 = 1 \\ x_1 + x_2 + x_3 = 3 \\ x_1 + 2x_2 + x_3 - x_4 = 2 \end{cases}$$

$$\left(\begin{array}{cccc|c} 3 & 2 & 3 & -2 & 1 \\ 1 & 1 & 1 & 0 & 3 \\ 1 & 2 & 1 & -1 & 2 \end{array} \right) \xrightarrow{E^{13}} \left(\begin{array}{cccc|c} 1 & 2 & 1 & -1 & 2 \\ 1 & 1 & 1 & 0 & 3 \\ 3 & 2 & 3 & -2 & 1 \end{array} \right)$$

$$\xrightarrow{E^{+1+2}} \left(\begin{array}{cccc|c} 1 & 2 & 1 & -1 & 2 \\ 0 & -1 & 0 & 1 & 1 \\ 3 & 2 & 3 & -2 & 1 \end{array} \right) \xrightarrow{E^{-3 \cdot 1+3}} \left(\begin{array}{cccc|c} 1 & 2 & 1 & -1 & 2 \\ 0 & -1 & 0 & 1 & 1 \\ 0 & -4 & 0 & 1 & -5 \end{array} \right)$$

$$\xrightarrow{E^{-4 \cdot 2+3}} \left(\begin{array}{cccc|c} 1 & 2 & 1 & -1 & 2 \\ 0 & -1 & 0 & 1 & 1 \\ 0 & 0 & 0 & -3 & -9 \end{array} \right) \xrightarrow{E_{3 \cdot 3}^{-1} \cdot E_j^{+2}} \left(\begin{array}{cccc|c} 1 & 2 & 1 & -1 & 2 \\ 0 & 1 & 0 & -1 & -1 \\ 0 & 0 & 0 & 1 & 3 \end{array} \right)$$

x_3 free

$x_4 = 3$

$x_2 - x_4 = -1 \Rightarrow x_2 = 2$

$x_1 + 2x_2 + x_3 - x_4 = 2$

$$\begin{aligned} \Rightarrow x_1 &= -2x_2 - x_3 + x_4 \\ &= -4 - x_3 + 2 = -2 - x_3 \end{aligned}$$

$$K_b = \left\{ \begin{pmatrix} 0 \\ 2 \\ 0 \\ 3 \end{pmatrix} + x_3 \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \mid x_3 \in \mathbb{R} \right\}$$

