## Smooth Maps

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Now that we have established the concept of local coordinates of a manifold M, we can define smooth maps *between* manifolds that preserve properties we have learned from advanced calculus.

## 1 Smooth Maps

Just like smooth functions, the smoothness of a map  $F: M \to N$  at a point  $p \in M$  is defined to be the smoothness of the *coordinate representation* of F at p and F(p):

**Definition 1.1.** Given smooth manifolds N, M of dimensions n, m respectively, a map  $F: N \to M$  is said to be smooth at p, if there are charts  $(U, \varphi)$ ,  $(V, \psi)$  at p and F(p) so that  $F(U) \subset V$  and

$$\psi \circ F \circ \varphi^{-1} : \varphi(U)(\subset \mathbb{R}^n) \to \psi(V)(\subset \mathbb{R}^m)$$

is a smooth map in the ordinary sense.

It is now clear that compatibilities of charts on N and M make the definition above independent of choice of coordinate: The following definitions can now be defined on manifolds:

**Definition 1.2.** A map  $F: N \to M$  is smooth if it is smooth at every point.

**Definition 1.3.** A map F : NtoM is called a diffeomorphism if it is smooth, bijective, and  $F^{-1}$  is smooth.

Constant maps from M to N, identity maps from M to itself, and inclusion maps of an open subset U to M, should all be smooth. Indeed, their coordinate representations are constant maps in Euclidean spaces. Some basic properties should hold true for smooth maps:

**Theorem 1.4.** Smooth maps are continuous.

**Theorem 1.5.** Composition of smooth maps is smooth.

It is also important to point out that smoothness is a local property.

**Proposition 1.6.** Let N and M be smooth manifolds and  $F : N \to M$  be a map.

- If every  $p \in M$  has an open neighborhood U such that  $F|_U$  is smooth, then F is smooth.
- If F is smooth, then its restriction to every open subset is smooth.

The proposition immediately implies

**Corollary 1.7.** Let M and N be smooth manifolds, and  $\{U_{\alpha}\}_{\alpha}$  be an open cover of M. Suppose that for each  $\alpha$ , there exists smooth functions  $F_{\alpha} : U_{\alpha} \to N$  so that for all  $\alpha, \beta$ ,

$$F_{\alpha}|_{U_{\alpha}\cap U_{\beta}} = F_{\beta}|_{U_{\alpha}\cap U_{\beta}}.$$

Then, there exists a smooth function  $F: M \to N$  so that  $F_{U_{\alpha}} = F_{\alpha}$ .

Let's study some example of smooth maps and diffeomorphisms.

Diffeomorphisms are basically the "identifiers" of smooth manifolds without concerns of metrics. Though a manifold may have many distinct smooth structures, they may be related to each other via diffeomorphisms. It is a fascinating (and very deep) subject to classify smooth type of a topological manifold, i.e. smooth structures up to diffeomorphisms.

It is not difficult to show the un-surprising fact that dimensions and boundaries are invariants under diffeomorphisms:

**Theorem 1.8.** An *m*-dimensional smooth manifolds can not be diffeomorphic to an *n*-dimensional manifolds unless n = m.

**Theorem 1.9.** Suppose M and N are smooth manifolds with a diffeomorphism  $F: M \to N$ . Then  $F(\partial M) = \partial N$  and F restricts to a diffeomorphism from IntM to IntN.